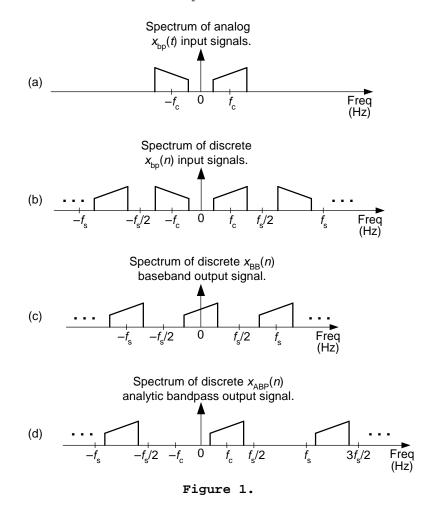
## Generating Complex Baseband and Analytic Bandpass Signals by Richard Lyons, Nov. 2011

There are so many different time- and frequency-domain methods for generating complex baseband and analytic bandpass signals that I had trouble keeping those techniques straight in my mind. Thus, for my own benefit, I created a kind of *reference* table showing those methods. I present that table for your viewing pleasure in this blog.

For clarity, I define a complex baseband signal as follows: derived from an input analog  $x_{bp}(t)$  bandpass signal whose spectrum is shown in Figure 1(a), or discrete input  $x_{bp}(n)$  bandpass signal whose spectrum is shown in Figure 1(b), a complex baseband signal is an  $x_{BB}(n)$  sequence whose spectrum is that shown in Figure 1(c). The sample rate of an  $x_{bp}(n)$  input sequence is defined as  $f_s$  Hz.



Based on the same analog  $x_{bp}(t)$  or discrete  $x_{bp}(n)$  input bandpass signal, an analytic bandpass signal is an  $x_{ABP}(n)$  sequence whose spectrum is that shown in Figure 1(d).

I realize that, by strict definition, an analytic signal has no negativefrequency spectral energy. And because our  $x_{ABP}(n)$  output bandpass signal is a discrete sequence it has spectral replications in its negative-frequency spectral region—So calling  $x_{ABP}(n)$  an analytic signal seems incorrect. We'll bypass that controversy by saying that a discrete sequence is *analytic* if it has no spectral energy in the frequency range of  $-f_s/2$  to zero Hz. Table 1, below, presents my Hit Parade of complex baseband and analytic bandpass signal generation methods. In that table "LPF" means a lowpass, linear-phase, tapped-delay line, FIR filter. All discrete Fourier transforms (DFTs) are implemented with radix-2 fast Fourier transforms (FFTs).

Table 1:	Complex	baseband	and	analvtic	bandpass	signal	generation	methods
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Process	Input/Output	Comments
Quadrature Sampling $x_{cos}(t)$ LPF $i(t)$ A/D $x_{l}(n)$ $x_{bp}(t)$ $cos(2\pi f_c t)$ $f_s$ $x_{sin}(t)$ LPF $q(t)$ A/D $x_{q}(n)$ $-sin(2\pi f_c t)$ $x_{BB}(n) = x_{l}(n) + jx_{q}(n)$	Input: analog bandpass signal centered at $f_c$ Hz, with sample rate of $f_s$ Hz Output: discrete complex $x_{BB}(n)$ baseband signal, centered at zero Hz, with sample rate of $f_s$ Hz.	Uses analog mixing and analog lowpass filters. Difficult to control the exact phase delays and gains of the $i(t)$ and $q(t)$ signals.
Quadrature Sampling $x_{bp}(t)$ A/D $x_{bp}(n)$ $x_{cos}(n)$ $PF \rightarrow x_{l}(n)$ $f_{s} = 4f_{c} = 1/t_{s}$ $x_{sin}(n)$ $PF \rightarrow x_{Q}(n)$ $-sin(2\pi n/4)$ $x_{BB}(n) = x_{l}(n) + jx_{Q}(n)$	<b>Input:</b> analog bandpass signal centered at $f_c$ Hz, with sample rate of $f_s$ Hz. <b>Output:</b> discrete complex $x_{BB}(n)$ baseband signal, centered at zero Hz, with sample rate of $f_s$ Hz.	All-digital downconversion facilitates exact control of phases and gains of the $x_I(n)$ and $x_Q(n)$ signals. A/D's $f_s$ sample rate normally equal to $4f_c$ , but setting $f_s = 0.8f_c$ allows bandpass sampling to reduce the $f_s$ sample rate. $f_s$ must greater than twice the bandwidth of $x_{bp}(t)$ . See [1] or Section 8.9 of [2].
Discrete Complex Downconversion $\begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \end{array} \\ $	Input: discrete real bandpass signal centered at $f_s/4$ Hz, with sample rate of $f_s$ Hz. Output: discrete complex $x_{BB}(n)$ baseband signal, centered at zero Hz, with sample rate of $f_s/4$ Hz.	Uses a time-domain Hilbert transformer and a half-band highpass FIR filter. If $h_{\text{hilb}}(k)$ has an odd number of taps, then half its coefficients will be zero-valued. See [3] or Section 13.43 of [2].

Table 1 Cont'd:

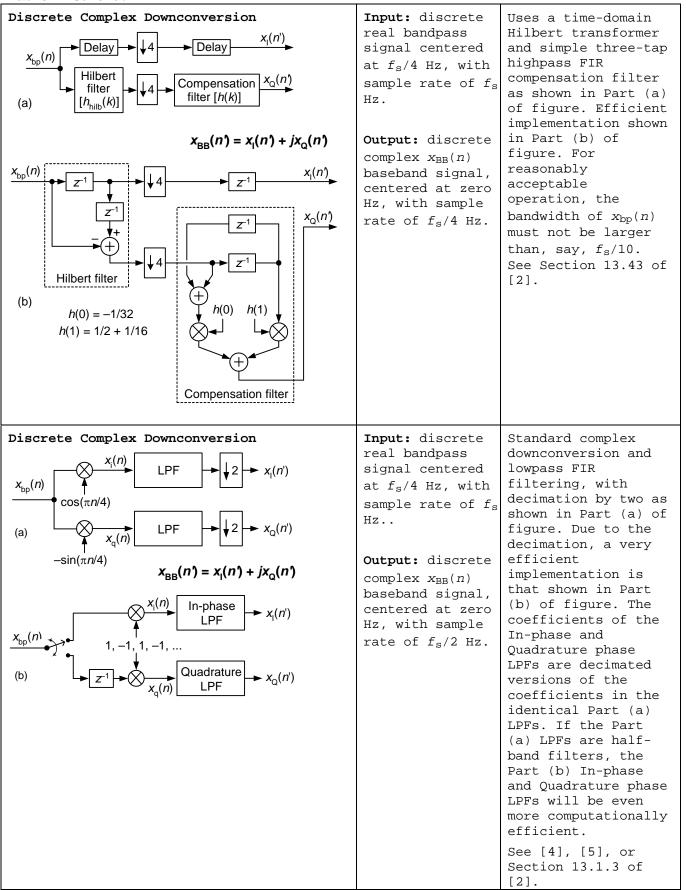
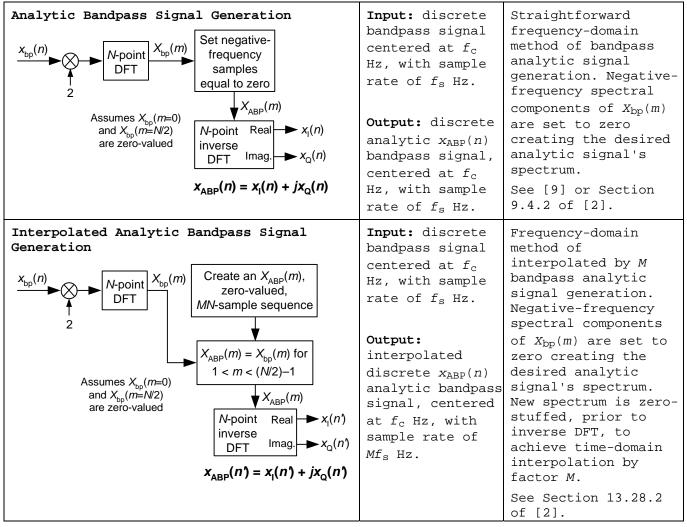


Table 1 Cont'd:

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Discrete Complex Downconversion $x_{bp}(n)$ $y_{DFT}$ $x_{bp}(m)$ Set negative- frequency samples equal to zero Assumes $X_{bp}(m=0)$ and $X_{bp}(m=N/2)$ are zero-valued $X_{BB}(m)$ Circular rotate all samples in negative-freq direction $X_{BB}(m)$ N-point Real inverse DFT Imag. $x_{Q}(n)$ $x_{BB}(n) = x_{I}(n) + jx_{Q}(n)$	Input: discrete real bandpass signal centered at $f_c$ Hz, with sample rate of $f_s$ Hz. Output: discrete complex $x_{BB}(n)$ baseband signal, centered at zero Hz, with sample rate of $f_s$ Hz.	Negative-frequency components of $x_{bp}(n)$ are attenuated in the frequency domain. Frequency downconversion performed by shifting (rotating) the frequency-domain indices of the positive-frequency spectral samples prior to inverse DFT.
Discrete Complex Downconversion $x_{bp}(n)$ 2 $X_{bp}(m)$ Set negative- frequency samples equal to zero $X_{ABP}(m)$ N-point Real inverse DFT Imag. D $X_{BB}(n) = x_{l}(n) + jx_{Q}(n)$	Input: discrete real bandpass signal centered at $kf_s/D$ Hz, with sample rate of $f_s$ Hz. Output: discrete complex $x_{BB}(n)$ baseband signal, centered at zero Hz, with sample rate of $f_s/D$ Hz.	Negative-frequency components of $x_{bp}(n)$ are attenuated in the frequency domain. Frequency downconversion performed by decimation in the time domain. See Section 13.29 of [2].
Analytic Bandpass Signal Generation $x_{bp}(n)$ $(N-1)$ -sample delay $x_{l}(n)$ $N$ -tap FIR, $h_{hilb}(k)$ , $x_{Q}(n)$ Hilbert transformer $x_{Q}(n)$ $x_{ABP}(n) = x_{l}(n) + jx_{Q}(n)$	<b>Input:</b> discrete bandpass signal centered at $f_c$ Hz, with sample rate of $f_s$ Hz. <b>Output:</b> discrete analytic $x_{ABP}(n)$ bandpass signal, centered at $f_c$ Hz, with sample rate of $f_s$ Hz.	Standard time- domain, tapped-delay line, FIR Hilbert transform method of discrete analytic bandpass signal generation. For proper time synchronization of $x_{I}(n)$ and $x_{Q}(n)$ , N must be an odd number-in which case half the $h_{hilb}(k)$ coefficients will be zero-valued. See Note 61 of [7] or Section 9.4.1 of [2].

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Analytic Bandpass Signal Generation	Input: discrete	A prototype lowpass
$x_{\rm bp}(n)$ $h_{\rm cos}(k)$ , real FIR filter	bandpass signal	filter (LPF) is designed to have a
$[\text{Real part of } h_{\text{BP}}(k)] \longrightarrow x_{l}(n)$	centered at $f_c$ Hz, with sample	two-sided bandwidth
	· -	slightly greater
$h_{sin}(k)$ , real FIR filter	rate of $f_s$ Hz.	than the bandwidth
$[\text{Imag. part of } h_{\text{BP}}(k)] \longrightarrow X_{\text{Q}}(n)$		of $x_{bp}(n)$ . The LPF's
	Output: discrete	coefficients are
$x_{ABP}(n) = x_{I}(n) + jx_{Q}(n)$	analytic $x_{ABP}(n)$	multiplied by cosine
	bandpass signal,	and sine sequences
Mindauina tha tua acta af filtan	centered at $f_{\rm c}$	whose frequencies
Windowing the two sets of filter coefficients will minimize passband	Hz, with sample	are $f_{c}$ Hz, creating
magnitude differences between the $h_{cos}(k)$	rate of $f_{\rm s}$ Hz.	a positive-frequency
		complex $h_{\rm bp}(k)$
and $h_{sin}(k)$ filters. (This method has slightly improved aggregate (overall)		bandpass filter. If
negative frequency attenuation compared to		$f_{\rm c} = f_{\rm s}/4$ then half the LPF coefficients
the following $A(k)$ and $B(k)$ dual filter		will be zero-valued.
method.)		Using a half-band
		LPF, if possible,
		further enhances
		computational
		efficiency.
		See [6], Note 62 of
		[7], or Section 9.5
		of [2].
Analytic Bandpass Signal Generation	Input: discrete	Clay Turner's method
$x_{\rm bp}(n)$	bandpass signal	of designing two orthogonal real
$\Delta p(r) = p(r)$		
A(k)	centered at $f_{c}$	_
	Hz, with sample	bandpass filters,
$\begin{array}{c} \hline A(k) \\ \hline B(k) \\ \hline B(k$	_	_
$B(k) \longrightarrow X_{Q}(n)$	Hz, with sample	bandpass filters, that when combined yield a positive- frequency complex
	Hz, with sample rate of $f_{ m s}$ Hz.	bandpass filters, that when combined yield a positive- frequency complex filter. If filters
$B(k) \longrightarrow X_Q(n)$	Hz, with sample rate of $f_s$ Hz. Output: discrete	bandpass filters, that when combined yield a positive- frequency complex filter. If filters are centered at $f_s/4$
$B(k) \longrightarrow X_{Q}(n)$	Hz, with sample rate of $f_{ m s}$ Hz.	bandpass filters, that when combined yield a positive- frequency complex filter. If filters are centered at $f_s/4$ and have an even
$B(k) \rightarrow x_{Q}(n)$ $x_{ABP}(n) = x_{I}(n) + jx_{Q}(n)$	Hz, with sample rate of $f_{s}$ Hz. Output: discrete analytic $x_{ABP}(n)$ bandpass signal,	bandpass filters, that when combined yield a positive- frequency complex filter. If filters are centered at $f_s/4$ and have an even number of taps, then
$B(k) \longrightarrow x_{Q}(n)$ $x_{ABP}(n) = x_{I}(n) + jx_{Q}(n)$ The $A(k)$ and $B(k)$ filters have guaranteed equal magnitude responses. $B[k]$ coefficients are a reversed-ordered	Hz, with sample rate of $f_s$ Hz. Output: discrete analytic $x_{ABP}(n)$	bandpass filters, that when combined yield a positive- frequency complex filter. If filters are centered at $f_s/4$ and have an even number of taps, then half the $A[k]$ and
The $A(k)$ and $B(k)$ filters have guaranteed equal magnitude responses. $B[k]$ coefficients are a reversed-ordered version of the $A[k]$ coefficients (reduces	Hz, with sample rate of $f_{\rm S}$ Hz. Output: discrete analytic $x_{\rm ABP}(n)$ bandpass signal, centered at $f_{\rm C}$	bandpass filters, that when combined yield a positive- frequency complex filter. If filters are centered at $f_s/4$ and have an even number of taps, then half the $A[k]$ and B[k] coefficients
The $A(k)$ and $B(k)$ filters have guaranteed equal magnitude responses. $B[k]$ coefficients are a reversed-ordered version of the $A[k]$ coefficients (reduces	Hz, with sample rate of $f_s$ Hz. Output: discrete analytic $x_{ABP}(n)$ bandpass signal, centered at $f_c$ Hz, with sample	bandpass filters, that when combined yield a positive- frequency complex filter. If filters are centered at $f_s/4$ and have an even number of taps, then half the $A[k]$ and
$B(k) \longrightarrow x_{Q}(n)$ $x_{ABP}(n) = x_{I}(n) + jx_{Q}(n)$ The $A(k)$ and $B(k)$ filters have guaranteed equal magnitude responses. $B[k]$	Hz, with sample rate of $f_s$ Hz. Output: discrete analytic $x_{ABP}(n)$ bandpass signal, centered at $f_c$ Hz, with sample	bandpass filters, that when combined yield a positive- frequency complex filter. If filters are centered at $f_s/4$ and have an even number of taps, then half the $A[k]$ and B[k] coefficients will be zero-valued. Phase responses of A[k] and $B[k]$
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Table 1 Cont'd:



For completeness, I mention that DSP pioneer Charles Rader proposed a computationally-efficient analytic bandpass signal generation method (See [10] or Note 66 in [7]) where both its  $x_{I}(n)$  and  $x_{Q}(n)$  output channels have identical frequency magnitude responses, however that scheme does not exhibit a linear-phase frequency response. As such, I didn't include it in Table 1.



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